sponding direction as in FIG. 1. Thus, the frame parts 1 are on top of each other by forming a bunch. The bunch-like placement of the frame parts 1 of the device can be seen in a more illustrative manner in FIG. 3, which presents the situation according to FIG. 2 in the "X" direction, i.e., an edge view, as seen from the direction X. In the example, the third frame part 1c is located on top of the first frame part 1a and the second frame part 1b is located below the first frame part, i.e. on the opposite side from the third frame part.

[0039] The series of figures formed by FIGS. 4 to 9 shows the phases connected to opening and closing the structure according to an embodiment of the invention. In the series of figures, FIG. 5 shows the embodiment according to FIG. 4 seen from the direction X, as well as in figure pairs 6 and 7, and 8 and 9. For the sake of clarity, additional references differing from other figures are used in the figure sequence in order to specify the surfaces of the frame parts 1. In FIGS. 4, 6 and 8 the first surface of the first frame part 1a is marked with A1 and the second surface with A2. Correspondingly, the first surface of the second frame part 1b is marked with B1 and the second surface with B2, and the first surface of the third frame part 1c is marked with C1 and the second surface with C2.

[0040] In figure pair 4 and 5 the device is closed, in which case the first surface C1 of the third frame part 1c is visible to the user (seen from the direction according to FIG. 4).

[0041] In FIGS. 6 and 7 two other frame parts 1a, 1b are folded from under the third frame part 1c next to the third part in such a manner that the first surface C1 of the third part 1c and the second surface B2 of the second part 1b are visible. The second frame part 1b and the first frame part 1a are on top of each other in such a manner that the first surfaces B1 and A1 are opposite each other. Next, the second frame part 1b is moved from on top of the first frame part 1ato a position that can be seen in FIGS. 8 and 9. Thus, the first surface A1 of the first part 1a, the first surface B1 of the second part 1b and the first surface C1 of the third part 1c are visible. In the example, all three frame parts 1a, 1b and 1c set next to each other in such a manner that their first surfaces 1a, 1b and 1c form a substantially uniform and even surface. All three frame parts 1a, 1b and 1c are as thick as each other in the example, in which case a substantially evenly thick structure is formed by the opened device. It is, however possible to, if necessary, form the different frame parts 1 as different in their thickness and/or fluctuating in their surface profile.

[0042] In the above-presented embodiments the frame parts 1 are uniform in such a manner that the sides setting on top of each other in the closed form substantially correspond to each other in their form. Thus, the appearance of the device substantially corresponds to the form of a single frame part 1, as can be detected in FIGS. 2 and 4. In the example, the thickness of the device corresponds to the combined thickness of the overlapping parts 1, as can be detected, for example, in FIGS. 3 and 5.

[0043] It is also possible to form at least one frame part 1 in a different form than the other frame parts. Thus, in such embodiments the frame parts 1 do not set entirely on top of each other in the closed form of the device. For example, FIGS. 10 and 11 show such an embodiment. In the example, one of the frame parts 1b of the device is larger in its area than the two other frame parts 1a, 1c. In FIG. 10 the structure is presented open and in FIG. 11 closed. As can be detected from the figures, in this example a part of the buttons 4 of the user interface in the second frame part 1b can be reached by the user both when the device is open and when the device is closed.

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[0044] In the above-presented embodiment, the angle between the axis lines of the opening structures 2, such as, for example, hinge structures, is substantially 120 degrees, which is marked in FIG. 6. An angle of the size in question between the hinge structures 2 enables, among other things, the embodiment described above in FIGS. 1 and 2, where the appearance of the closed device corresponds substantially to the form of an individual frame part 1. FIGS. 12 and 13 show an embodiment, where the angle between the hinge structures 2 is not 120 degrees. The frame parts 1 of the structure in question are connected to each other when the device is open, as shown in FIG. 12. When closing the device, the frame parts 1 do note set entirely on top of each other, as FIG. 13 presents. In the embodiment according to FIGS. 12 and 13 one frame part 1b is larger than the other frame parts 1a, 1c, in which case when the device is closed, some of the surface of this largest frame part remains visible on the background of the other frame parts setting on top of it. As can be detected from FIGS. 12 and 13, the buttons 4 of a user interface placed on this kind of an area can be reached by the user both when the device is open and when the device is closed.

[0045] The size of the angle between the axis lines of the opening structures 2, such as, for example, hinge structures, may vary a greatly depending on the application. For example, the size of the angle can be 70 to 170 degrees. In several embodiments the size of the angle is 100 to 140 degrees. Thus, the angle between the opening directions of the second frame part 1b and the third frame part 1c is 40 to 80 degrees. When the angle between the axis lines of the hinge structures 2 is substantially 120 degrees, the structure is possible to form as symmetric in the manner presented by FIGS. 1 and 2.

[0046] In the above examples the frame parts 1 are connected with hinge structures 2. It is possible to also use other kinds of opening structures 2 for connecting frame parts 1. FIGS. 14 to 17 show an embodiment of the invention, where the first opening device 2 is a hinge structure and the second opening structure is a slide structure. The presented slide structure 2 enables the linear movement of the frame part 1c. In FIG. 14 the device is in a closed position, in which case the user has access to the first user interface. In FIG. 15 the device is presented in a mid-position, where two frame parts 1a, 1b connected by a hinge structure 2 have been set next to each other. In FIG. 16 the third frame part 1c within the first frame part 1a has been slid partly outside the first frame part 1a. FIG. 17 shows the device in an open position, in which case all three frame parts 1a, 1b, 1c are set in the vicinity of each other. It is naturally possible to open the device in an order differing from what is presented above, such as, for example, by sliding the third frame part 1c open first. The opening structure 2 is also possible to be implemented in several different ways. For example, a slide structure may enable the sliding of frame parts 1 on top of each other or within each other.

[0047] In the above-presented examples the buttons 4 are arranged on the main surfaces of the frame parts 1. The